Pulsar Lecture Slides

Minimum Magnetic Field Strength (at surface of pulsar)

- P_{rad} (power radiated by magnetic dipole)
- -È (rate of loss of rotational energy)
- Assuming all loss of rotational energy goes into magnetic dipole radiation:

$$P_{rad} = -\dot{E}$$

Minimum Magnetic Field Strength

$$P_{rad} = -\dot{E}$$

• We have expressions for each of these- plug in:

$$\frac{2}{3c^3}(BR^3\sin\alpha)^2 \left(\frac{4\pi^2}{P^2}\right)^2 = \frac{4\pi^2 I\dot{P}}{P^3}$$

 Everything is a constant/feature of pulsar, except for Bsolve for B:

Minimum Magnetic Field Strength

Solving for B, we get
$$B = \left(\frac{3c^3I}{8\pi^2R^6\sin^2\alpha}\right)^{\frac{1}{2}}(P\dot{P})^{\frac{1}{2}}$$

However, sin^2 ranges between 0 and 1, so

$$B > \left(\frac{3c^3I}{8\pi^2R^6}\right)^{\frac{1}{2}} (P\dot{P})^{\frac{1}{2}}$$

• Plugging in the values for a canonical pulsar (R~10^6 cm, I ~ 10^45 g/cm^2) we get
$$\left(\frac{B}{gauss} \right) > \left(3.2 \times 10^{19} \right) \left(\frac{P\dot{P}}{s} \right)^{\frac{1}{2}}$$

- We want an approximation of the age of a pulsar.
- We can get one by integrating $P\dot{P}$ over the pulsar's lifetime.
- Rearranging our magnetic field expression for $P\dot{P}$, we get

$$P\dot{P} = \frac{8\pi^2 R^6 (B\sin\alpha)^2}{3c^3 I}$$

- This is a constant, as long as B is constant in time!
-But is it?

Is B Constant in Time?

For a canonical pulsar, $P\approx 0.1s, \dot{P}\approx 10^{-15}\frac{s}{s}, \ddot{P}\approx 10^{-29}\frac{s}{s^2}$

a) What is the minimum magnetic field at the surface?

b) Calculate the rate of change of the magnetic field. Is it a reasonable approximation that the magnetic field is constant?

Solution

a)
$$B = (3.2 \times 10^{19}) \times ((0.1)(10^{-15}))^{1/2} = 3.2 \times 10^{11} gauss$$

b)
$$\frac{\partial B}{\partial t} = (1.6 \times 10^{19}) \times (P\dot{P})^{-1/2} \times (P\ddot{P} + \dot{P}^2)$$
$$\frac{\partial B}{\partial t} = 0.00176 \frac{gauss}{s}$$

- So, B is mostly constant in time, and PP is as well.
- Get an expression for τ using a trick:

$$P\dot{P}dt = P(\dot{P}dt) = PdP$$

Integrate both sides over the lifetime of the pulsar:

From t = 0 (birth) to to to to term (current age)
$$\int_0^{\tau} P\dot{P}dt = \int_{P_0}^{P} PdP \quad \text{From P = P0 (period at birth) to to P = P (current period)}$$

$$P\dot{P}\int_0^\tau dt = \int_{P_0}^P PdP$$

$$P\dot{P}\tau = \frac{1}{2}(P^2 - P_0^2)$$

$$\tau = \frac{P}{2\dot{P}}$$

ASSUMPTIONS

- B is constant in time
- P0 << P

- Is the approximation of τ more accurate for young pulsars or old pulsars?
 - Old: we assumed P0 << P.
 - Old pulsars have had more time to spin down, period has changed more since birth

Braking Index

- $\bullet \quad \text{Back to} \quad P_{rad} = -\dot{E}$
- Using different forms (angular velocity, not period) and rearranging, get expected proportionality: $\dot{\Omega} \propto \Omega^3$

ERA 6.1.8

- However, this is a theoretical value, and our observations might not match up: $\dot{\Omega} \propto \Omega^n$
- Braking index n gives evolution of pulsar spin over time.
 Observed values ranging from 1.4 to 3

Braking Index

- Why the discrepancy?
- We assumed that $P_{rad} = -\dot{E}$: very simplistic model of pulsar radiation
 - Magnetosphere- plasma surrounding pulsar
 - Changing magnetic field over time
 - Timing noise & glitches

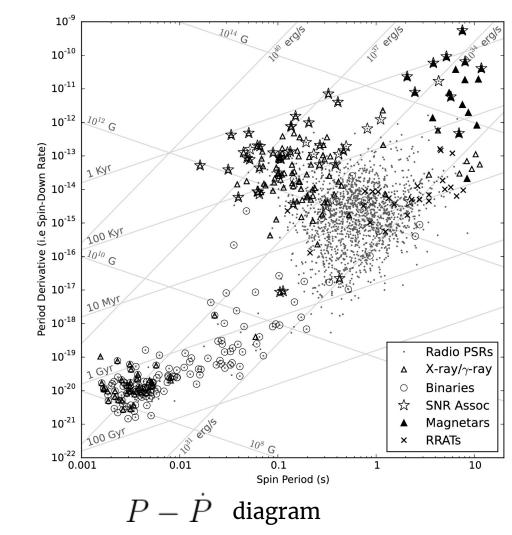
Braking Index

• Starting from $\dot{\Omega} \propto \Omega^n$

$$n = \frac{\Omega\Omega}{\dot{\Omega}^2} = 2 - \frac{PP}{\dot{P}^2}$$

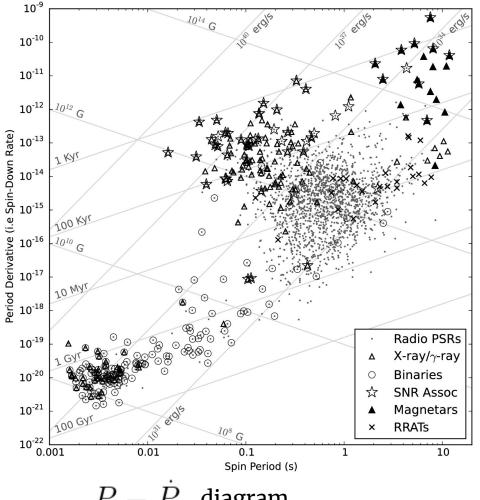
Lives of Pulsars

- -Ė, Bmin, τ, all determined by location on diagram
- Different populations
- Lines of constant
 Bmin, -Ė, τ



Lives of Pulsars

 How will pulsar evolution over time look on the diagram?

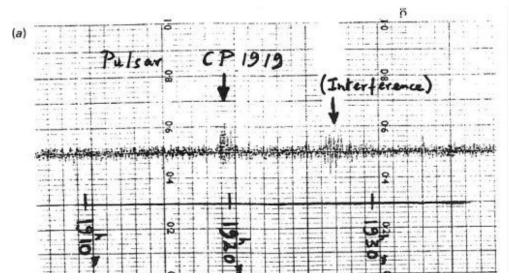


diagram

Pulsar Astronomy

- 1. Detection
- 2. Timing
- 3. Science!

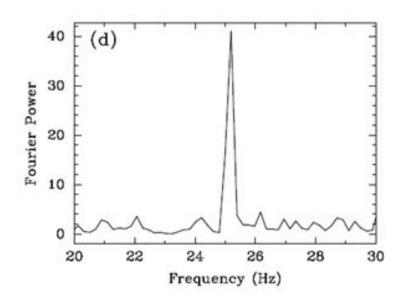
- Pulsars are weak and inconsistent
- Searching for pulsars- can't always just point a telescope and be sure you'll see it
- How to find one, then?



- Pulsar signal should be dispersed and periodic
- Dispersion- low frequency part of signal moves slower than high frequency part, because of ISM

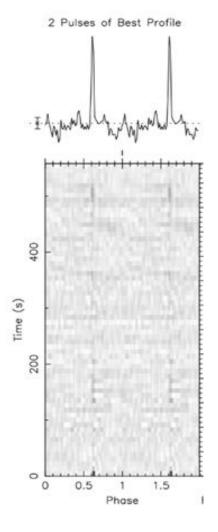
- Pulsar signal should be dispersed and periodic
- Dispersion- low frequency part of signal moves slower than high frequency part, because of ISM
- Search for periodic signals
 - Take FT of data (which should be periodic)
 - FT of periodic function (ie sin/cos)?

- Search for periodic signals
 - Take FT of data
 - Not quite delta function, but peak at good approx. of frequency/period



Signal is still weak- how do we boost our S/N...?

- "Fold" data at best period
- Pulse should arrive at the same point in the rotation every time (over short timescales)
- Signal adds up more quickly than noise

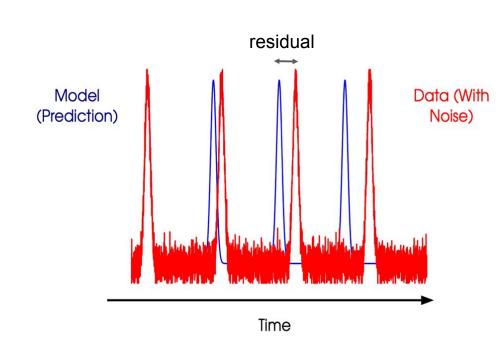


Timing

- Get a good period at one small chunk of time
 - For accurate science, need extremely precise values of P and its derivatives at all times
 - As well as other aspects- RA, Dec, DM, orbital parameters for binary systems

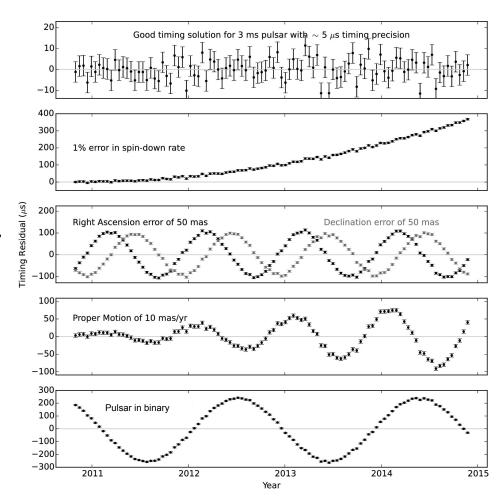
Timing

- Obtain times of arrival (TOAs)at what precise time did pulse arrive at telescope
 - Compare model of when you think it'll arrive vs.
 when it actually does (residuals)
 - By adding more to your model, you want to minimize residualsminimize error in model



Timing

- If your model is good, your residuals will be randomly distributed around 0
- If not, tweak parameters of your model to get better residuals, rinse and repeat



Why Pulsars?

- Extreme physics- i.e. densities and magnetic fields
- Gravitational wave detection
 - Array of well-timed pulsars across sky
- Tests of GR
 - Binary pulsar system- loses energy to gravitational radiation; period decreases
- Also: electron density of the galaxy, plasma physics, radio emission mechanisms, extremely dense matter, high-precision timing, data analysis, signal processing....

